

# Asymptotic preserving well-balanced schemes for hyperbolic systems of balance laws

G. RUSSO \*

Several physical systems are described by evolutionary partial differential equations which have the structure of hyperbolic systems of balance laws of the form

$$(1) \quad U_t + F(U)_x = \frac{1}{\epsilon} R(U),$$

where  $U(x, t) \in \mathbb{R}^M$  and the right hand side may contain a stiff relaxation term as the parameter  $\epsilon$  becomes small. Such systems are efficiently solved by implicit-explicit schemes (IMEX) [1], which treat explicitly the non-stiff hyperbolic term, and implicitly the stiff source term [2]. If  $R$  is a relaxation, this means that i) there exists a matrix  $Q \in \mathbb{R}^{m \times M}$ ,  $m < M$ , such that  $QR(U) = 0 \forall U \in \mathbb{R}^M$  and ii) the solutions of  $R(U) = 0$  can be uniquely expressed as  $U = E(u)$ , with  $u = QU \in \mathbb{R}^m$ . As a result, as  $\epsilon \rightarrow 0$  the system formally relaxes to a smaller system of conservation laws of the form

$$(2) \quad u_t + f(u)_x = 0,$$

with  $f = QF(E(u))$ . This reduction for vanishing  $\epsilon$  can be made rigorous if a suitable subcharacteristic condition is satisfied [3]. Such a property has been adopted to construct the *relaxation methods* [4].

A scheme for the numerical solution of system (1) which becomes a consistent scheme for system (2) as the relaxation parameter vanishes is said to be *Asymptotic Preserving* (AP) [5, 2]

For moderate value of  $\epsilon$ , there might be non-trivial stationary solutions of problem (1). If one is interested in solving problems whose solution is a small perturbation of a stationary one, then it is highly advisable to adopt a *Well-Balanced* scheme (WB), i.e. a scheme which is able to maintain, within machine precision or to great accuracy, the (discrete or continuous) stationary solution, otherwise truncation error may be comparable or even greater than the small perturbation one is interested in [6].

If the source term contains a stiff relaxation and a non stiff term, i.e. for systems of the form

$$(3) \quad U_t + F(U)_x = \frac{1}{\epsilon} R(U) + G(U, x),$$

in the limit of vanishing  $\epsilon$  the system relaxes to a lower dimensional system of balance laws of the form

$$(4) \quad u_t + f(u)_x = g(u, x),$$

where  $g(u, x) = QG(E(u), x)$ . In such cases nontrivial equilibria appear for all values of  $\epsilon$ . Effective treatment of such problems for small to vanishing values of  $\epsilon$  requires schemes which are at the same time AP and WB.

A slightly different class of problems appears when both the hyperbolic term and the source are (equally) stiff:

$$(5) \quad \epsilon U_t + F(U)_x = R(U).$$

In such cases the system may relax to a stationary solution in a very short time. If one is interested in efficiently capturing the stationary solution, then it is advisable to adopt an implicit (or semi-implicit) scheme which is at the same time asymptotic preserving and well-balanced.

---

\*Department of Mathematics and Computer Science, University of Catania, Italy. Email: giovanni.russo1@unict.it

The purpose of the talk is to illustrate how to combine IMEX of semi-implicit schemes in time with modern high-order well-balanced discretization [7], thus obtaining asymptotic-preserving well-balanced schemes for the classes of problems mentioned above. Finite volume or finite difference discretization in space will be adopted. When the exact solution of the stationary problem is not known, a numerical stationary solution is obtained adopting locally Runge-Kutta collocation methods [8]. Several numerical examples will be presented, which show the effectiveness of the new methods.

The research is conducted in collaboration with Sebastiano Boscarino (University of Catania) and with Carlos Parés, Manuel Castro, and Irene Gomez-Bueno (University of Malaga).

## Acknowledgements

This research has been partially supported by the Italian Ministry of Instruction, University and Research (MIUR) with funds coming from PRIN Project 2017 (No. 2017KKJP4X entitled “Innovative numerical methods for evolutionary partial differential equations and applications”).

## References

- [1] U-M. Ascher, S. J. Ruuth, R.J. Spiteri, Implicit-explicit Runge-Kutta methods for time-dependent partial differential equations, *Applied Numerical Mathematics* 25(2-3), pp.151-167 (1997).
- [2] L.Pareschi, G.Russo, Implicit-Explicit Runge-Kutta schemes and applications to hyperbolic systems with relaxation. *Journal of Scientific Computing*, vol. 25, p. 129-155 (2005).
- [3] Gui-Qiang Chen, C David Levermore, Tai-Ping Liu, , Hyperbolic conservation laws with stiff relaxation terms and entropy, *Communications on Pure and Applied Mathematics* 47 (6), 787–830 (1994).
- [4] Shi Jin, Zhouping Xin, The relaxation schemes for systems of conservation laws in arbitrary space dimensions, *Communications on Pure and Applied Mathematics*, (1995).
- [5] Shi Jin, Asymptotic preserving (AP) schemes for multiscale kinetic and hyperbolic equations: a review. *Rivista di Matematica della Università di Parma* 3, 177-216 (2012).
- [6] A. Bermúdez and M. E. Vázquez, Upwind methods for hyperbolic conservation laws with source terms., *Computers & Fluids*, 23(8):1049-1071 (1994).
- [7] M. J. Castro, T. Morales, C. Parés, Well-balanced schemes and path-conservative numerical methods, *Handbook of Num. Anal.*, 18: 131-175 (2017).
- [8] Irene Gómez-Bueno., Manuel Jesús Castro Díaz, Carlos Parés, and Giovanni Russo, Collocation Methods for High-Order Well-Balanced Methods for Systems of Balance Laws, *Mathematics* 9(15), p.1799 (2021).